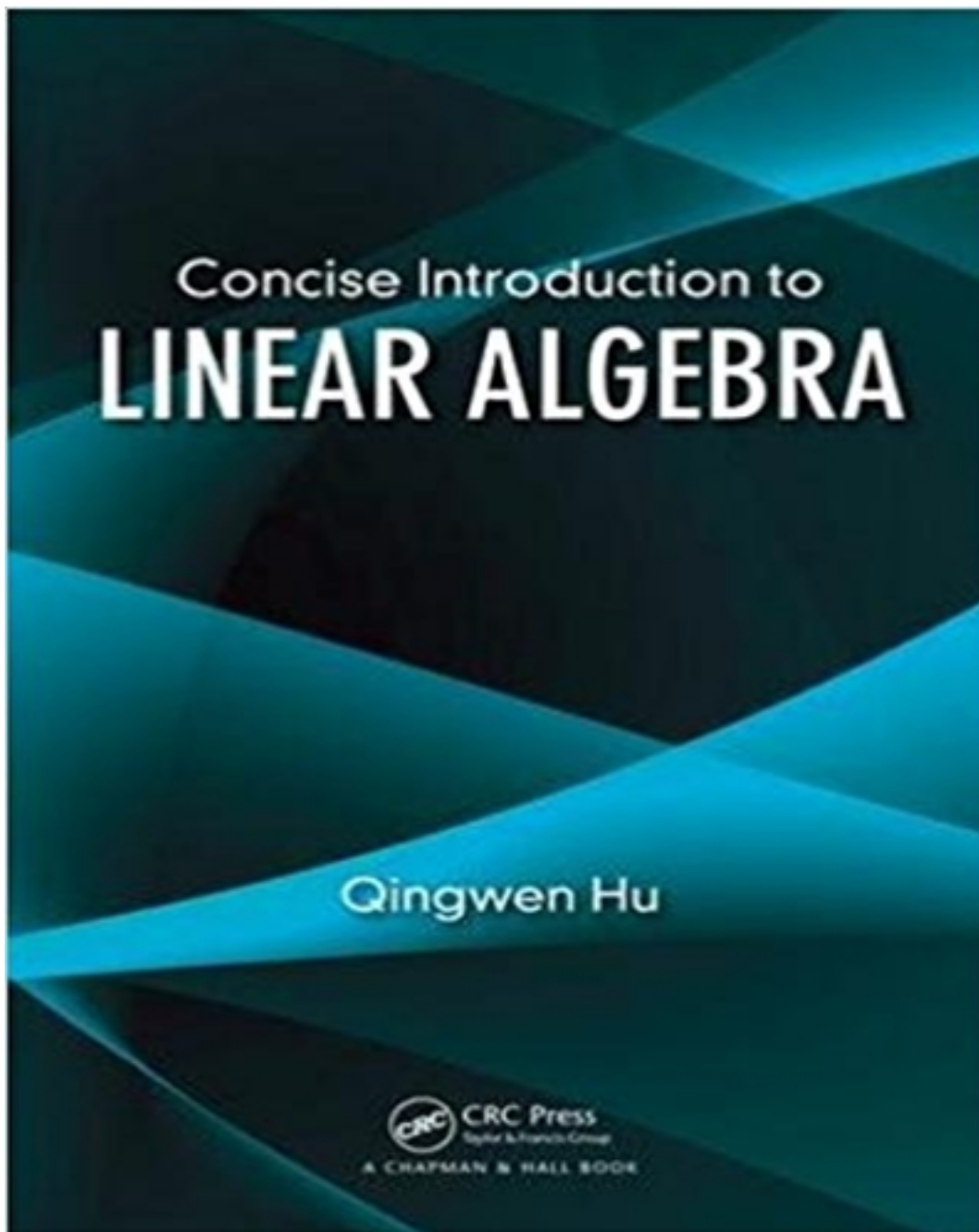


# Solutions for Concise Introduction to Linear Algebra 1st Edition by Hu

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# Solutions

# Chapter 2

## Solving linear systems

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### 2.1 Vectors and linear equations

#### Exercise 2.1.1.

1. Redo Example 2.1.1 with the first elementary row operation  $R_2 - R_1$ .

**Solution:**

System	Matrix representation	Elementary matrix
$\begin{cases} x - y = 1 \\ x + y = 2 \end{cases}$	$\begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$	
$\Downarrow R_2 - R_1$		$E_1 = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$
$\begin{cases} x - y = 1 \\ 2y = 1 \end{cases}$	$\begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$	
$\Downarrow \frac{1}{2}R_2$	$\begin{bmatrix} 1 & -1 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$	$E_3 = \begin{bmatrix} 1 & 0 \\ 0 & \frac{1}{2} \end{bmatrix}$
$\begin{cases} x - y = 1 \\ y = \frac{1}{2} \end{cases}$	$\begin{bmatrix} 1 & 0 \\ 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$	
$\Downarrow R_1 + R_2$	$\begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ \frac{1}{2} \end{bmatrix}$	$E_4 = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$
$\begin{cases} x = \frac{3}{2} \\ y = \frac{1}{2} \end{cases}$	$\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ \frac{1}{2} \end{bmatrix}$	

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \frac{3}{2} \\ \frac{1}{2} \end{bmatrix}.$$

2. Determine whether the following matrices are in reduced row echelon form and row echelon form, respectively:

$$a) \begin{bmatrix} 1 & 0 & 0 & 9 & -2 \\ 0 & 1 & 0 & -2 & \frac{1}{2} \\ 0 & 0 & 1 & -5 & \frac{1}{2} \end{bmatrix}, \quad b) \begin{bmatrix} 1 & 0 & 0 & 9 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & -5 \end{bmatrix}, \quad c) \begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 1 & 0 & \frac{1}{2} \\ 0 & 0 & 1 & \frac{1}{2} \end{bmatrix}.$$

**Solution:** a) and b) are in reduced row echelon form (hence also in row echelon form). c) is in row echelon form.  $\square$

3. Solve the following systems using Gauss–Jordan eliminations:

$$a) \begin{cases} x + 3z = 1 \\ 2x + 3y = 3 \\ 4y + 5z = 5 \end{cases} \quad b) \begin{cases} x + 2y + 3z = 1 \\ 2x + 3y + 4z = 3 \\ 3x + 4y + 5z = 5 \end{cases} \quad c) \begin{cases} x + 2y + 3z = 1 \\ 2x + 3y + 4z = 3 \\ 5x + 9y + 13z = 7 \end{cases}$$

**Solution:** a) We re-write the system of linear equations in the matrix form  $\mathbf{Ax} = \mathbf{b}$ , where

$$A = \begin{bmatrix} 1 & 0 & 3 \\ 2 & 3 & 0 \\ 0 & 4 & 5 \end{bmatrix}, \quad \mathbf{x} = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \quad \text{and} \quad \mathbf{b} = \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}.$$

Then the corresponding augmented matrix is

$$[A : \mathbf{b}] = \begin{bmatrix} 1 & 0 & 3 & 1 \\ 2 & 3 & 0 & 3 \\ 0 & 4 & 5 & 5 \end{bmatrix}.$$

By the elementary row operations on  $[A : \mathbf{b}]$  we have

$$\begin{aligned} \begin{bmatrix} 1 & 0 & 3 & 1 \\ 2 & 3 & 0 & 3 \\ 0 & 4 & 5 & 5 \end{bmatrix} &\xrightarrow{R_2 - 2R_1} \begin{bmatrix} 1 & 0 & 3 & 1 \\ 0 & 3 & -6 & 1 \\ 0 & 4 & 5 & 5 \end{bmatrix} \\ &\xrightarrow{R_2/3} \begin{bmatrix} 1 & 0 & 3 & 1 \\ 0 & 1 & -2 & \frac{1}{3} \\ 0 & 4 & 5 & 5 \end{bmatrix} \\ &\xrightarrow{R_3 - 4R_2} \begin{bmatrix} 1 & 0 & 3 & 1 \\ 0 & 1 & -2 & \frac{1}{3} \\ 0 & 0 & 13 & \frac{11}{3} \end{bmatrix} \end{aligned}$$

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$$\begin{aligned} &\xrightarrow{R_3/13} \begin{bmatrix} 1 & 0 & 3 & 1 \\ 0 & 1 & -2 & \frac{1}{3} \\ 0 & 0 & 1 & \frac{11}{39} \end{bmatrix} \\ &\xrightarrow[\begin{matrix} R_2+2R_3 \\ R_1-3R_3 \end{matrix}]{\quad} \begin{bmatrix} 1 & 0 & 0 & \frac{6}{39} \\ 0 & 1 & 0 & \frac{35}{39} \\ 0 & 0 & 1 & \frac{11}{39} \end{bmatrix}. \end{aligned}$$

Then we have an equivalent system with augmented matrix

$$\begin{bmatrix} 1 & 0 & 0 & \frac{6}{39} \\ 0 & 1 & 0 & \frac{35}{39} \\ 0 & 0 & 1 & \frac{11}{39} \end{bmatrix}.$$

The solution is

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} \frac{6}{39} \\ \frac{35}{39} \\ \frac{11}{39} \end{bmatrix}.$$

b) We re-write the system of linear equations in the matrix form  $A\mathbf{x} = \mathbf{b}$ , where

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 3 & 4 & 5 \end{bmatrix}, \mathbf{x} = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \text{ and } \mathbf{b} = \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}.$$

Then the corresponding augmented matrix is

$$[A : \mathbf{b}] = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 2 & 3 & 4 & 3 \\ 3 & 4 & 5 & 5 \end{bmatrix}.$$

By the elementary row operations on  $[A : \mathbf{b}]$  we have

$$\begin{aligned} &\begin{bmatrix} 1 & 2 & 3 & 1 \\ 2 & 3 & 4 & 3 \\ 3 & 4 & 5 & 5 \end{bmatrix} \xrightarrow[\begin{matrix} R_2-2R_1 \\ R_3-3R_1 \end{matrix}]{\quad} \begin{bmatrix} 1 & 2 & 3 & 1 \\ 0 & -1 & -2 & 1 \\ 0 & -2 & -4 & 2 \end{bmatrix} \\ &\xrightarrow{(-1) \cdot R_2} \begin{bmatrix} 1 & 2 & 3 & 1 \\ 0 & 1 & 2 & -1 \\ 0 & -2 & -4 & 2 \end{bmatrix} \\ &\xrightarrow[\begin{matrix} R_3+2R_2 \\ R_1-2R_2 \end{matrix}]{\quad} \begin{bmatrix} 1 & 0 & -1 & 3 \\ 0 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \end{aligned}$$

Then we have an equivalent system with augmented matrix

$$\begin{bmatrix} 1 & 0 & -1 & 3 \\ 0 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

The solution is

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}, t \in \mathbb{R}.$$

c) We re-write the system of linear equations in the matrix form  $A\mathbf{x} = \mathbf{b}$ , where

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 5 & 9 & 13 \end{bmatrix}, \mathbf{x} = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \text{ and } \mathbf{b} = \begin{bmatrix} 1 \\ 3 \\ 7 \end{bmatrix}.$$

Then the corresponding augmented matrix is

$$[A : \mathbf{b}] = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 2 & 3 & 4 & 3 \\ 5 & 9 & 13 & 7 \end{bmatrix}.$$

By the elementary row operations on  $[A : \mathbf{b}]$  we have

$$\begin{aligned} \begin{bmatrix} 1 & 2 & 3 & 1 \\ 2 & 3 & 4 & 3 \\ 5 & 9 & 13 & 7 \end{bmatrix} &\xrightarrow[\substack{R_2-2R_1 \\ R_3-5R_1}]{\substack{R_2-2R_1 \\ R_3-5R_1}} \begin{bmatrix} 1 & 2 & 3 & 1 \\ 0 & -1 & -2 & 1 \\ 0 & -1 & -2 & 2 \end{bmatrix} \\ &\xrightarrow{(-1) \cdot R_2} \begin{bmatrix} 1 & 2 & 3 & 1 \\ 0 & 1 & 2 & -1 \\ 0 & -1 & -2 & 2 \end{bmatrix} \\ &\xrightarrow[\substack{R_3+R_2 \\ R_1-2R_2}]{\substack{R_3+R_2 \\ R_1-2R_2}} \begin{bmatrix} 1 & 0 & -1 & 3 \\ 0 & 1 & 2 & -1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \end{aligned}$$

Then we have an equivalent system with augmented matrix

$$\begin{bmatrix} 1 & 0 & -1 & 3 \\ 0 & 1 & 2 & -1 \\ 0 & 0 & 0 & 1 \end{bmatrix},$$

where the last equation is contradictory. The system has no solution. □

□

4. Consider a linear system  $Ax = b$  with  $A$  an  $m \times n$  matrix and  $b$  an  $m \times 1$  matrix. Is it true if there is more than one solution for  $x$  in  $\mathbb{R}^n$ , there must be infinitely many? You may use the fact that

$$\begin{aligned} A(x + y) &= Ax + Ay \\ A(tx) &= tAx, \end{aligned}$$

for every  $x, y \in \mathbb{R}^n$  and  $t \in \mathbb{R}$ ,

which is called the **linearity** of matrix multiplication.

**Solution:** Let  $x_1$  and  $x_2$  be distinct solutions. Then  $A(x_1 - x_2) = Ax_1 - Ax_2 = 0$  and for every  $t \in \mathbb{R}$ , we have

$$A(x_1 + t(x_1 - x_2)) = Ax_1 + tA(x_1 - x_2) = b.$$

Hence  $x = x_1 + t(x_1 - x_2)$ ,  $t \in \mathbb{R}$  are all solutions of  $Ax = b$ . That is,  $Ax = b$  has infinitely many solutions.  $\square$

5. Let  $k$  be a real number. Consider the following linear system of equations:

$$\begin{cases} x_2 + 2x_3 + x_4 = 1 \\ 2x_1 + x_2 + 3x_3 = 2 \\ x_1 + 4x_3 + 2x_4 = 3 \\ kx_2 + x_4 = 1. \end{cases} \quad (2.1)$$

Find all possible values of  $k$  such that system (2.1) i) has a unique solution; ii) has no solutions and iii) has infinitely many solutions.

**Solution:** We re-write the system of linear equations in the matrix form  $Ax = \mathbf{b}$ , where

$$A = \begin{bmatrix} 0 & 1 & 2 & 1 \\ 2 & 1 & 3 & 0 \\ 1 & 0 & 4 & 2 \\ 0 & k & 0 & 1 \end{bmatrix}, \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \text{ and } \mathbf{b} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 1 \end{bmatrix}.$$

Then the corresponding augmented matrix is

$$[A : \mathbf{b}] = \begin{bmatrix} 0 & 1 & 2 & 1 & 1 \\ 2 & 1 & 3 & 0 & 2 \\ 1 & 0 & 4 & 2 & 3 \\ 0 & k & 0 & 1 & 1 \end{bmatrix}.$$

By the elementary row operations on  $[A : \mathbf{b}]$  we have

$$\begin{aligned} \begin{bmatrix} 0 & 1 & 2 & 1 & 1 \\ 2 & 1 & 3 & 0 & 2 \\ 1 & 0 & 4 & 2 & 3 \\ 0 & k & 0 & 1 & 1 \end{bmatrix} &\xrightarrow{R_3 \leftrightarrow R_1} \begin{bmatrix} 1 & 0 & 4 & 2 & 3 \\ 2 & 1 & 3 & 0 & 2 \\ 0 & 1 & 2 & 1 & 1 \\ 0 & k & 0 & 1 & 1 \end{bmatrix} \\ &\xrightarrow{R_2 - 2R_1} \begin{bmatrix} 1 & 0 & 4 & 2 & 3 \\ 0 & 1 & -5 & -4 & -4 \\ 0 & 1 & 2 & 1 & 1 \\ 0 & k & 0 & 1 & 1 \end{bmatrix} \\ &\xrightarrow{\substack{R_4 - kR_2 \\ R_3 - R_2}} \begin{bmatrix} 1 & 0 & 4 & 2 & 3 \\ 0 & 1 & -5 & -4 & -4 \\ 0 & 0 & 7 & 5 & 5 \\ 0 & 0 & 5k & 1 + 4k & 1 + 4k \end{bmatrix} \end{aligned}$$

$$\begin{aligned} &\xrightarrow{R_3/7} \begin{bmatrix} 1 & 0 & 4 & 2 & 3 \\ 0 & 1 & -5 & -4 & -4 \\ 0 & 0 & 1 & 5/7 & 5/7 \\ 0 & 0 & 5k & 1+4k & 1+4k \end{bmatrix} \\ &\xrightarrow{R_4-(5k) \cdot R_3} \begin{bmatrix} 1 & 0 & 4 & 2 & 3 \\ 0 & 1 & -5 & -4 & -4 \\ 0 & 0 & 1 & 5/7 & 5/7 \\ 0 & 0 & 0 & 1+3k/7 & 1+3k/7 \end{bmatrix}. \end{aligned}$$

Then we have an equivalent system with augmented matrix

$$\begin{bmatrix} 1 & 0 & 4 & 2 & 3 \\ 0 & 1 & -5 & -4 & -4 \\ 0 & 0 & 1 & 5/7 & 5/7 \\ 0 & 0 & 0 & 1+3k/7 & 1+3k/7 \end{bmatrix},$$

- i) If  $1+3k/7 \neq 0$ , that is,  $k \neq -7/3$  the original system has a unique solution;
- ii) If  $1+3k/7 = 0$ , that is,  $k = -7/3$  the original system has infinitely many solutions.

Therefore, for every  $k \in \mathbb{R}$ , the system has at least one solution. □

## 2.2 Matrix operations

### Exercise 2.2.1.

1. Let  $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ ,  $B = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix}$ . i) Compute  $AB$ . ii) Does  $BA$  exist?

**Solution:** i)

$$AB = \begin{bmatrix} 1 & 2 & 1 & 2 \\ 3 & 4 & 3 & 4 \end{bmatrix}.$$

- ii)  $BA$  does not exist since their sizes do not match as  $B$  is  $2 \times 4$  and  $A$  is  $2 \times 2$ . □

2. Let  $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ ,  $B = \begin{bmatrix} 1 & -1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix}$ . i) Compute  $AB$ . ii) If  $B$  is block partitioned into  $B = [B_1 : B_2]$ , is it true  $AB = [AB_1 : AB_2]$ ?

**Solution:** i)

$$AB = \begin{bmatrix} 3 & 1 & 2 & 1 \\ 7 & 1 & 4 & 3 \end{bmatrix}$$

- ii) According to the definition of matrix multiplication, the statement is true. □

3. Show Lemma 2.2.6.

**Solution:** Follow the approach for the proof of Theorem 2.2.5.  $\square$

4. Let  $A = [a_1 : a_2 \cdots : a_n]$ ,  $B = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$  be  $m \times n$  and  $n \times r$  matrices. Show

that  $AB = a_1b_1 + a_2b_2 + \cdots + a_nb_n$ .

**Solution:** By the definition of matrix multiplication we have

$$\begin{aligned} (AB)_{i,j} &= a_{i,1}b_{1,j} + a_{i,2}b_{2,j} + \cdots + a_{i,n}b_{n,j} \\ &= (a_1b_1)_{i,j} + (a_2b_2)_{i,j} + \cdots + (a_nb_n)_{i,j} \\ &= (a_1b_1 + a_2b_2 + \cdots + a_nb_n)_{i,j}. \end{aligned}$$

Therefore, we have  $AB = a_1b_1 + a_2b_2 + \cdots + a_nb_n$ .  $\square$

5. Let  $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ ,  $B = \begin{bmatrix} 1 & -1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix}$ . Use Question 4 to compute  $AB$ .

**Solution:** Let  $A = [a_1 : a_2]$ ,  $B = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$

$$\begin{aligned} AB &= a_1b_1 + a_2b_2 \\ &= \begin{bmatrix} 1 \\ 3 \end{bmatrix} [1 \quad -1 \quad 0 \quad 1] + \begin{bmatrix} 2 \\ 4 \end{bmatrix} [1 \quad 1 \quad 1 \quad 0] \\ &= \begin{bmatrix} 1 & -1 & 0 & 1 \\ 3 & -3 & 0 & 3 \end{bmatrix} + \begin{bmatrix} 2 & 2 & 2 & 0 \\ 4 & 4 & 4 & 0 \end{bmatrix} \\ &= \begin{bmatrix} 3 & 1 & 2 & 1 \\ 7 & 1 & 4 & 3 \end{bmatrix}. \end{aligned}$$

$\square$

6. Let  $A$  and  $B$  be  $m \times n$  and  $n \times r$  matrices. Show that i) every column of  $AB$  is a linear combination of the columns of  $A$ ; ii) every row of  $AB$  is a linear combination of the rows of  $B$ .

**Solution:** Let  $A = [a_1 : a_2 \cdots : a_n]$ ,  $B = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$  be  $m \times n$  and  $n \times r$  matrices.

$$(AB)_{i,j} = a_{i,1}b_{1,j} + a_{i,2}b_{2,j} + \cdots + a_{i,n}b_{n,j}.$$

The  $j$ -th column of  $AB$  is

$$(AB)_j = a_1b_{1,j} + a_2b_{2,j} + \cdots + a_nb_{n,j},$$

which is a linear combination of the columns of  $A$ .  $\square$



7. Let  $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ . Find all matrices  $B$  such that  $AB = BA$ .

**Solution:** Let  $B = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ . Then  $BA = AB$  leads to a linear system of  $x = (a, b, c, d) \in \mathbb{R}^4$ :

$$\begin{cases} 3b - 2c = 0 \\ 2a + 3b - 2d = 0 \\ 3a + 3c - 3d = 0 \\ 3b - 2c = 0. \end{cases}$$

Using Gauss-Jordan elimination, we obtain the solution

$$x = s \begin{bmatrix} -1 \\ 2/3 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \quad s, t \in \mathbb{R}.$$

That is,

$$B = \begin{bmatrix} t - s & 2s/3 \\ s & t \end{bmatrix}.$$

8. Let  $A$  and  $B$  be  $n \times n$  matrices. Explain that in general we have  $(A + B)(A - B) \neq A^2 - B^2$  and  $(A + B)^2 \neq A^2 + 2AB + B^2$ .

**Solution:** We note that in general,  $AB \neq BA$ . So  $(A + B)(A - B) = A^2 - AB + BA - B^2 \neq A^2 - B^2$  and  $(A + B)^2 \neq A^2 + 2AB + B^2$  if  $AB \neq BA$ .

9. Let  $A$  be an  $n \times n$  matrix. Define  $V = \{B : AB = BA\}$ . Show that i)  $V \neq \emptyset$ ; ii) if  $B_1 \in V$  and  $B_2 \in V$ , then every linear combination of  $B_1$  and  $B_2$  is in  $V$ .

**Solution:** i) Since  $AI = IA$  and  $I \in V$ , we have  $V \neq \emptyset$ .

ii) If  $B_1 \in V$  and  $B_2 \in V$ , then for every  $s \in \mathbb{R}$  and  $t \in \mathbb{R}$ , we have

$$\begin{aligned} (sB_1 + tB_2)A &= sB_1A + tB_2A \\ &= sAB_1 + tAB_2 \\ &= A(sB_1 + tB_2). \end{aligned}$$

Therefore, we have  $sB_1 + tB_2 \in V$ . We have shown that  $V$  is a vector space.  $\square$

10. Give an example that  $A^2 = 0$  but  $A \neq 0$ .

**Solution:**

$$A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}.$$

We have  $A^2 = 0$  but  $A \neq 0$ .

11. Give an example that  $A^2 = I$  but  $A \neq \pm I$ .

**Solution:**

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}.$$

We have  $A^2 = I$  but  $A \neq \pm I$ .

12. Let  $A$  be an  $n \times n$  matrix. If we want to define a limit  $\lim_{m \rightarrow \infty} A^m$ , how would you define the closeness (distance) between matrices?

**Solution:** If we identify  $A$  as a vector in  $\mathbb{R}^{n^2}$ . Then we can borrow norms on  $\mathbb{R}^{n^2}$  for defining the distance between matrices. For example, we can define

$$\text{distance}(A, B) = \left( \sum_{i=1}^n \sum_{j=1}^n (a_{ij} - b_{ij})^2 \right)^{\frac{1}{2}},$$

where  $a_{ij}$  and  $b_{ij}$  are entries at  $(i, j)$ -position of  $A$  and  $B$ , respectively.  $\square$

## 2.3 Inverse matrices

### Exercise 2.3.1.

1. Determine whether or not the following matrices are invertible. Find the inverse of each matrix if it exists.

$$a) \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}, \quad b) \begin{bmatrix} -1 & 2 \\ 3 & 6 \end{bmatrix}, \quad c) \begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix}.$$

**Solution:** a)  $\begin{bmatrix} -2 & 1 \\ \frac{3}{2} & -\frac{1}{2} \end{bmatrix}$ , b)  $\begin{bmatrix} -\frac{1}{2} & \frac{1}{6} \\ \frac{1}{4} & \frac{1}{12} \end{bmatrix}$ , c) not invertible.

$\square$

2. Determine whether or not the following matrices are invertible. Find the inverse of each matrix if it exists.

$$a) \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \quad b) \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 3 & 1 \end{bmatrix}, \quad c) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

**Solution:** a)  $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$ , b)  $\begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 6 & -3 & 1 \end{bmatrix}$ , c)  $\begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{6} & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$\square$

3. Determine whether or not the following matrices are invertible. Find the inverse of each matrix if it exists.

$$a) \begin{bmatrix} 1 & 2 & 0 \\ 3 & 4 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad b) \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 2 \\ 0 & 3 & 6 \end{bmatrix}, \quad c) \begin{bmatrix} 1 & 2 & 0 \\ 3 & 6 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

**Solution:** a)  $\begin{bmatrix} -2 & 1 & 0 \\ \frac{3}{2} & -\frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}$ , b)  $\begin{bmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{2} & \frac{1}{6} \\ 0 & \frac{1}{4} & \frac{1}{12} \end{bmatrix}$ , c) not invertible.

□

4. For the given matrix  $A$ , use elimination to find  $A^{-1}$  and record each elementary row operation and the corresponding elementary matrix at the same time.

$$A = \begin{bmatrix} 3 & 0 & 1 \\ 2 & 4 & 2 \\ 1 & -1 & 5 \end{bmatrix}.$$

**Solution:**

$\begin{bmatrix} 3 & 0 & 1 & 1 & 0 & 0 \\ 2 & 4 & 2 & 0 & 1 & 0 \\ 1 & -1 & 5 & 0 & 0 & 1 \end{bmatrix}$	Row operation	Elementary Matrix
↓	$R_1 \leftrightarrow R_3$	$E_1 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$
$\begin{bmatrix} 1 & -1 & 5 & 0 & 0 & 1 \\ 2 & 4 & 2 & 0 & 1 & 0 \\ 3 & 0 & 1 & 1 & 0 & 0 \end{bmatrix}$	Row operation	Elementary Matrix
↓	$R_2 - 2R_1$	$E_2 = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$
$\begin{bmatrix} 1 & -1 & 5 & 0 & 0 & 1 \\ 0 & 6 & -8 & 0 & 1 & -2 \\ 3 & 0 & 1 & 1 & 0 & 0 \end{bmatrix}$	Row operation	Elementary Matrix
↓	$R_3 - 3R_1$	$E_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix}$
$\begin{bmatrix} 1 & -1 & 5 & 0 & 0 & 1 \\ 0 & 6 & -8 & 0 & 1 & -2 \\ 0 & 3 & -14 & 1 & 0 & -3 \end{bmatrix}$	Row operation	Elementary Matrix
↓	$R_3 - R_2/2$	$E_4 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -\frac{1}{2} & 1 \end{bmatrix}$

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$\begin{bmatrix} 1 & -1 & 5 & 0 & 0 & 1 \\ 0 & 6 & -8 & 0 & 1 & -2 \\ 0 & 0 & -10 & 1 & -\frac{1}{2} & -2 \end{bmatrix}$	Row operation	Elementary Matrix
$\Downarrow$	$R_3/(-10)$	$E_5 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -\frac{1}{10} \end{bmatrix}$
$\begin{bmatrix} 1 & -1 & 5 & 0 & 0 & 1 \\ 0 & 6 & -8 & 0 & 1 & -2 \\ 0 & 0 & 1 & -\frac{1}{10} & \frac{1}{20} & \frac{1}{5} \end{bmatrix}$	Row operations	Elementary Matrices
$\Downarrow$	$R_1 - 5R_3$	$E_6 = \begin{bmatrix} 1 & 0 & -5 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix},$
	$R_2 + 8R_3$	$E_7 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 8 \\ 0 & 0 & 1 \end{bmatrix}$
$\begin{bmatrix} 1 & -1 & 0 & \frac{1}{2} & -\frac{1}{4} & 0 \\ 0 & 6 & 0 & -\frac{4}{5} & \frac{14}{10} & -\frac{2}{5} \\ 0 & 0 & 1 & -\frac{1}{10} & \frac{1}{20} & \frac{1}{5} \end{bmatrix}$	Row operation	Elementary Matrix
$\Downarrow$	$R_2/6$	$E_8 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{6} & 0 \\ 0 & 0 & 1 \end{bmatrix}$
$\begin{bmatrix} 1 & -1 & 0 & \frac{1}{2} & -\frac{1}{4} & 0 \\ 0 & 1 & 0 & -\frac{4}{30} & \frac{14}{60} & -\frac{2}{30} \\ 0 & 0 & 1 & -\frac{1}{10} & \frac{1}{20} & \frac{1}{5} \end{bmatrix}$	Row operation	Elementary Matrix
$\Downarrow$	$R_1 + R_2$	$E_9 = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$
$\begin{bmatrix} 1 & 0 & 0 & \frac{11}{30} & \frac{1}{60} & -\frac{2}{30} \\ 0 & 1 & 0 & -\frac{4}{30} & \frac{14}{60} & -\frac{2}{30} \\ 0 & 0 & 1 & -\frac{1}{10} & \frac{1}{20} & \frac{1}{5} \end{bmatrix}$		

Then we have

$$A^{-1} = \frac{1}{60} \begin{bmatrix} 22 & 1 & -4 \\ -8 & 14 & -4 \\ -6 & 3 & 12 \end{bmatrix},$$

which can be written as the product of elementary matrices  $E_9E_8E_7E_6E_5E_4E_3E_2E_1$ .

□

5. For what values of  $\lambda \in \mathbb{R}$  is the following matrix

$$A = \begin{bmatrix} 3 & 0 & 1 \\ 2 & 4 & 2 \\ 1 & -1 & \lambda \end{bmatrix}$$

invertible?

**Solution:** We use elimination to determine when the reduced row echelon form is an identity matrix. We have

$$\begin{aligned} A = \begin{bmatrix} 3 & 0 & 1 \\ 2 & 4 & 2 \\ 1 & -1 & \lambda \end{bmatrix} &\xrightarrow{R_2 \leftrightarrow R_1} \begin{bmatrix} 2 & 4 & 2 \\ 3 & 0 & 1 \\ 1 & -1 & \lambda \end{bmatrix} \\ &\xrightarrow{R_1/2} \begin{bmatrix} 1 & 2 & 1 \\ 3 & 0 & 1 \\ 1 & -1 & \lambda \end{bmatrix} \\ &\xrightarrow{\substack{R_2 - 2R_1 \\ R_3 - R_1}} \begin{bmatrix} 1 & 2 & 1 \\ 0 & -6 & -2 \\ 0 & -3 & \lambda - 1 \end{bmatrix} \\ &\xrightarrow{R_2/(-6)} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & \frac{1}{3} \\ 0 & -3 & \lambda - 1 \end{bmatrix} \\ &\xrightarrow{R_3 + 3R_2} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & \frac{1}{3} \\ 0 & 0 & \lambda \end{bmatrix}. \end{aligned}$$

The reduced row echelon form of  $A$  is  $I$  if and only if  $\lambda \neq 0$ . That is,  $A$  is invertible if and only if  $\lambda \neq 0$ .

□

6. Let  $A$  be an  $n \times n$  matrix. If  $A = \begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_n \end{bmatrix}$  satisfies that  $r_2 = r_3 + r_1$ , is  $A$

invertible?

**Solution:**  $A$  is not invertible since using elementary eliminations to subtract  $r_1$  and  $r_3$  from  $r_2$  will result in a matrix with a zero row which is not invertible.

□

7. Let  $A$  be an  $n \times n$  matrix. If  $A = [c_1 : c_2 : \cdots : c_n]$  satisfies that  $c_2 = c_3 + c_1$ , is  $A$  invertible?

**Solution:** By the previous question,  $A^T$  is not invertible and hence  $A$  is not invertible.

□

8. Let  $v, w \in \mathbb{R}^n$  be vectors. Is the matrix  $A = \begin{bmatrix} \|v\| & 1 \\ |v \cdot w| & \|w\| \end{bmatrix}$  invertible?

**Solution:**  $A$  is not invertible if and only if  $\|v\| \cdot \|w\| = |v \cdot w|$ .  $\square$

9. Give an example of a  $3 \times 3$  dominant matrix and find its inverse.

10. Find a sufficient condition on  $a, b, c$  and  $d \in \mathbb{R}$  such that the matrix

$$A = \begin{bmatrix} a^2 + b^2 & 2ab \\ 2cd & c^2 + d^2 \end{bmatrix}$$

is invertible.

11. Let  $A = \begin{bmatrix} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$ . i) Compute  $A^2$ ; ii) Show that for every  $k \geq 3, k \in \mathbb{N}$ ,

$A^k = 0$ .

**Solution:**  $A^2 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$  and  $A^3 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ . Therefore for every  $k \geq 3, k \in \mathbb{N}, A^k = A^3 A^{k-3} = 0$ .  $\square$

12. Let  $A$  be an  $n \times n$  matrix. Show that if  $A^k = 0$ , then  $I - A$  is invertible and

$$(I - A)^{-1} = I + A + A^2 + \cdots + A^{k-1}.$$

**Solution:** Hint: We have  $(I - A)(I + A + A^2 + \cdots + A^{k-1}) = I$ .  $\square$

13. Let  $A$  be an  $n \times n$  matrix and  $A = tI + N, t \in \mathbb{R}$  with  $N^4 = 0$  for some  $k \in \mathbb{N}$ . Compute  $A^4$  in terms of  $t$  and  $N$ .

**Solution:** Note that  $tIN = N(tI)$ . We have  $A^4 = N^4 + (tI)N^3 + (tI)^2N^2 + (tI)^3N + (tI)^4 = tN^3 + t^2N^2 + t^3N + t^4I$ .  $\square$

14. Let  $D = \text{diag}\{\lambda_1, \lambda_2, \dots, \lambda_n\}$  be a diagonal matrix with the main diagonal entries  $\lambda_1, \lambda_2, \dots, \lambda_n$ . Show that  $D$  is invertible if and only if  $\lambda_i \neq 0$ , for every  $i = 1, 2, \dots, n$ .

**Solution:** Hint: if  $\lambda_i \neq 0$ , for every  $i = 1, 2, \dots, n$ , the reduced row echelon form of  $D$  is the identity matrix.  $\square$

15. Let  $A$  be an  $n \times n$  matrix. i) If  $A^3 = I$ , find  $A^{-1}$ ; ii) If  $A^k = I$  for some  $k \in \mathbb{N}$ , find  $A^{-1}$ ; iii) If  $A^k = 0$  for some  $k \in \mathbb{N}$ , is it possible that  $A$  is invertible?

**Solution:** i)  $A^{-1} = A^2$ , ii)  $A^{-1} = A^{k-1}$ , iii). No. Notice that  $AB$  is invertible if and only if both  $A$  and  $B$  are invertible, where  $A$  and  $B$  are square matrices of the same size.  $\square$

**16.** Show that  $A$  is invertible if and only if  $A^k$  is invertible for every  $k \in \mathbb{N}, k \geq 1$ .

**Solution:** Notice that  $AB$  is invertible if and only if both  $A$  and  $B$  are invertible. The conclusion follows.  $\square$

**17.** Let  $A$  and  $B$  be  $n \times n$  invertible matrices. i) Give an example to show that  $A+B$  may not be invertible; ii) Show that  $A+B$  is invertible if and only if  $A^{-1} + B^{-1}$  is invertible.

**Solution:** i) Let  $A = I$  and  $B = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$  be  $2 \times 2$  matrixes. Then  $A$  and  $B$  are both invertible while  $A+B = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$  is not invertible.

ii). Note that  $A+B = A(A^{-1} + B^{-1})B$ .  $A+B$  is invertible if and only if  $A^{-1} + B^{-1}$  is invertible.  $\square$

## 2.4 $LU$ decomposition

### Exercise 2.4.1.

**1.** Let  $-l_{ij}$  be the entry of the  $4 \times 4$   $E_{ij}^{-1}$  matrix below the main diagonal. Which one of the following products can be obtained by directly writing  $-l_{ij}$  into the  $(i, j)$  position of the products? i)  $E_{31}^{-1}E_{32}^{-1}E_{41}^{-1}E_{42}^{-1}E_{43}^{-1}$ ; ii)  $E_{32}^{-1}E_{21}^{-1}E_{31}^{-1}E_{42}^{-1}E_{43}^{-1}$ .

**Solution:** The point is that the row of the identity matrix to be added to another row should not be changed. i) Row 1, 2, 3 were not changed when they are used to change row 4 and row Row 1 and 2 were not changed when they are used to change row 3. So the matrix  $E_{31}^{-1}E_{32}^{-1}E_{41}^{-1}E_{42}^{-1}E_{43}^{-1}$  can be obtained by directly writing  $-l_{ij}$  into the  $(i, j)$  position of the products.

ii) Since row 2 were changed with  $E_{21}^{-1}$  before applying to  $E_{32}^{-1}$ ,  $E_{32}^{-1}E_{21}^{-1}E_{31}^{-1}E_{42}^{-1}E_{43}^{-1}$  can not be obtained by directly writing  $-l_{ij}$  into the  $(i, j)$  position of the products.  $\square$

**2.** Find the  $LU$  decomposition of

$$A = \begin{bmatrix} 3 & 0 & 1 \\ 2 & 4 & 2 \\ 1 & -1 & 5 \end{bmatrix}.$$

**Solution:** Using elementary eliminations we have

$$E_{32}E_{31}E_{21}A = \begin{bmatrix} 3 & 0 & 1 \\ 0 & 4 & \frac{4}{3} \\ 0 & 0 & 5 \end{bmatrix} := U,$$

where

$$E_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -\frac{2}{3} & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, E_{31} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -\frac{1}{3} & 0 & 1 \end{bmatrix}, E_{32} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & \frac{1}{4} & 1 \end{bmatrix}.$$

Then we have  $A = LU$ , where

$$L = E_{21}^{-1}E_{31}^{-1}E_{32}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ \frac{2}{3} & 1 & 0 \\ \frac{1}{3} & -\frac{1}{4} & 1 \end{bmatrix}.$$

□

**3.** Let  $b = (1, 2, 3)$  and  $A = \begin{bmatrix} 3 & 0 & 1 \\ 2 & 4 & 2 \\ 1 & -1 & 5 \end{bmatrix}$ . Use the  $LU$  decomposition of  $A$  to solve system  $Ax = b$ .

**Solution:** Since  $A = LU$ , we have  $LUx = b$ . Let  $Ux = y$ . Then  $Ly = b$  with solution  $y = (1, \frac{4}{3}, 3)$ . Solving  $Ux = y$  we have

$$x = \left( \frac{2}{15}, \frac{2}{15}, \frac{3}{5} \right).$$

□

**4.** Is it true that a matrix  $A$  does not have an  $LU$  decomposition? Justify your answer.

**Solution:** Yes, for example

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}.$$

□

## 2.5 Transpose and permutation

### Exercise 2.5.1.



1. Let  $A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix}$ . Find  $A^{-1}$  and  $A^T$ .

**Solution:**  $A$  is a permutation matrix and is orthogonal.

$$A^{-1} = A^T = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

□

2. Let  $A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}$ . i) Find  $AA^T$  and  $A^T A$ . ii) Determine which one of

$AA^T$  and  $A^T A$  is invertible. iii) If one of  $AA^T$  and  $A^T A$  is invertible, does it contradict Theorem 2.3.6?

**Solution:** i)

$$AA^T = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}, A^T A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

ii)  $A^T A$  is invertible.

iii) No. Theorem 2.3.6 is about square matrices.

□

3. Let

$$A = \begin{bmatrix} 0 & 1 & 2 & 3 \\ 1 & 2 & 3 & 4 \\ 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 6 \end{bmatrix}, B = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & 3 \\ 3 & 4 & 5 & 6 \\ 2 & 3 & 4 & 5 \end{bmatrix}.$$

i) Find a permutation matrix  $P_1$  such that  $B = P_1 A$ ; ii) Find a permutation matrix  $P_2$  such that  $A = P_2 B$ . iii) Compute  $P_1 P_2$  and  $P_2 P_1$ .

**Solution:** Examining how the rows of  $A$  were rearranged to obtain  $B$ , we have

$$P_1 = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix}, P_2 = P_1^T = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix}, P_1 P_2 = P_2 P_1 = I.$$

□

4. Let

$$A = \begin{bmatrix} 7 & 1 & 2 & 3 \\ 1 & 2 & 3 & 4 \\ 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 7 \end{bmatrix}.$$

Find a permutation matrix  $P$ , a lower triangular matrix  $L$  and a diagonal matrix  $D$  such that  $PA = LU$ .

**Solution:**

$$L = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1/7 & 13/25 & 1 & 0 \\ 2/7 & 19/25 & 1/2 & 1 \\ 3/7 & 1 & 0 & 0 \end{bmatrix}, U = \begin{bmatrix} 7 & 1 & 2 & 3 \\ 0 & 25/7 & 29/7 & 40/7 \\ 0 & 0 & 14/25 & 3/5 \\ 0 & 0 & 0 & -1/2 \end{bmatrix},$$

$$P = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

□

5. Let  $R_\theta = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$ . Show that  $R_\theta$  is an orthogonal matrix.

**Solution:**  $R_\theta$  is an orthogonal matrix since we have

$$R_\theta R_\theta^T = I.$$

□

6. Let  $x \in \mathbb{R}^n$  with  $x^T x = 1$ . Define the **Householder matrix** by

$$H = I - 2xx^T.$$

i) Show that  $H$  is an orthogonal matrix; ii) Show that  $H$  is symmetric.

**Solution:** i) Verify by the definition that  $H^T H = I$ . Indeed, we have

$$\begin{aligned} H^T H &= (I - 2xx^T)^T (I - 2xx^T) \\ &= (I - 2xx^T)(I - 2xx^T) \\ &= (I - 2xx^T) - 2xx^T(I - 2xx^T) \\ &= (I - 2xx^T) - 2xx^T + 4xx^T xx^T \\ &= I - 4xx^T + 4xx^T \\ &= I. \end{aligned}$$

ii)  $H^T = (I - 2xx^T)^T = H$ .  $H$  is symmetric.

□

7. Let  $S = \begin{bmatrix} I & A \\ A^T & O \end{bmatrix}$ , where  $I$  is  $m \times m$  and  $A$  is  $m \times n$ ,  $O$  the zero matrix. Find a block diagonal matrix  $D$  and block lower triangular matrix  $L$  such that

$$S = LDL^T.$$

**Solution:** Let  $L = \begin{bmatrix} I & O \\ -A^T & I \end{bmatrix}$ . We have

$$LS = \begin{bmatrix} I & O \\ -A^T & I \end{bmatrix} \begin{bmatrix} I & A \\ A^T & O \end{bmatrix} = \begin{bmatrix} I & A \\ O & -A^T A \end{bmatrix}.$$

Then

$$LSL^T = \begin{bmatrix} I & O \\ -A^T & I \end{bmatrix} \begin{bmatrix} I & A \\ A^T & O \end{bmatrix} \begin{bmatrix} I & -A \\ O & I \end{bmatrix} = \begin{bmatrix} I & O \\ O & -A^T A \end{bmatrix}.$$

□

8. Show that  $AA^T$  is invertible if and only if the rows of  $A$  are linearly independent.

**Solution:** We know that the columns of  $A$  are linearly independent if and only if  $A^T A$  is invertible. It follows that  $(A^T)^T A^T$  is invertible if and only if the columns of  $A^T$  are linearly independent. That is,  $AA^T$  is invertible if and only if the rows of  $A$  are linearly independent. □

9. We say  $A$  is **skew-symmetric** if  $A^T = -A$ . i) Show that if  $A$  is a skew-symmetric  $n \times n$  matrix then  $a_{ii} = 0$  for every  $i = 1, 2, \dots, n$ . ii) If  $A$  is both symmetric and skew-symmetric, then  $A = 0$ .

**Solution:** i) We have  $A^T = -A$ . Then it follows that for every  $i = 1, 2, \dots, n$ ,

$$(A^T)_{ii} = (A)_{ii} = (-A)_{ii} \Rightarrow a_{ii} = -a_{ii}.$$

We have  $a_{ii} = 0$  for every  $i = 1, 2, \dots, n$ .

ii) If  $A$  is both symmetric and skew-symmetric, then  $A^T = -A = A$ . That is,  $A = 0$ . □

10. Let  $A$  be an  $n \times n$  matrix. Show that i)  $A + A^T$  is symmetric; ii)  $A - A^T$  is skew-symmetric; iii) For every square matrix  $B$ , there exist a unique symmetric matrix  $B_1$  and a unique skew-symmetric matrix  $B_2$  such that  $B = B_1 + B_2$ .

**Solution:** i) Since  $(A + A^T)^T = A^T + A = A + A^T$ ,  $A + A^T$  is symmetric.

ii) Since  $(A - A^T)^T = A^T - A = -(A - A^T)$ ,  $A - A^T$  is skew-symmetric. □

11. A matrix is called **lower triangular** if every entry above the main diagonal is zero and is called **upper triangular** if every entry below the main diagonal is zero. Let  $A$  be an  $n \times n$  invertible matrix. i) Show that if  $A$  is lower

triangular,  $A^{-1}$  is also lower triangular; ii) Show that if  $A$  is upper triangular, then  $A^{-1}$  is also upper triangular.

**Solution:** i) We use matrix partition. Suppose  $A$  and  $B = A^{-1}$  are partitioned as following:

$$A = \begin{bmatrix} A_{11} & O \\ A_{21} & a_{nn} \end{bmatrix}, B = A^{-1} = \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & b_{nn} \end{bmatrix}.$$

Then we have

$$BA = \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & b_{nn} \end{bmatrix} \begin{bmatrix} A_{11} & O \\ A_{21} & a_{nn} \end{bmatrix} = \begin{bmatrix} B_{11}A_{11} + B_{12}A_{21} & B_{12}a_{nn} \\ B_{21}A_{11} + b_{nn}A_{21} & b_{nn}a_{nn} \end{bmatrix} = I_n,$$

where  $I_n$  is the  $n \times n$  identity matrix. Since  $a_{nn} \neq 0$ , we have  $B_{12} = O$ . It follows that  $B_{11}A_{11} = I_{n-1}$ . By the same token, we can show that right upper block of  $B_{11}$  is zero. Repeat the same argument on the sub-matrices of  $B_{11}$ , we obtain that  $B$  is lower triangular.

ii) Notice that if  $A$  is invertible we have  $(A^{-1})^T = (A^T)^{-1}$ . The statement follows from i).  $\square$

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